

## October 27

### Announcements

- Webassign 3.3, 4.1, 4.2 due next Thursday
- Sign sheet if you did worksheet 4, there's a good chance a problem similar to a problem on worksheet 4 will appear on midterm
- Worksheet 5 posted this weekend
- Watch videos 8,9 of 3blue1brown, determinants are mentioned. Think about it as signed volume.

### 3.3 Inverses

**Theorem:** Let  $A$  and  $B$  be invertible matrices and  $C$  and  $D$  be matrices. Then

- $A^{-1}$  is also invertible.
- $AB$  is invertible. The inverse is given by  $(AB)^{-1} = B^{-1}A^{-1}$ .
- If  $AC = AD$  then  $C = D$ .
- If  $CA = DA$  then  $C = D$ .

**Theorem:** Let  $A$  be a  $n \times n$  matrix. Let  $S$  be the columns of  $A$ . Let  $T(x) = Ax$ . Then the following are equivalent:

- $S$  spans  $\mathbb{R}^n$
- $S$  is linearly independent
- $Ax = b$  has a unique solution for all  $b \in \mathbb{R}^n$  given by  $x = A^{-1}b$ .
- $T$  is onto
- $T$  is one-to-one
- $T$  is invertible
- $A$  is invertible

The inverse of  $[a, b; c, d]$  is  $[d, -b; -c, a]/\det$ .

### Example

Solve the linear system  $3x_1 + x_2 = 3$  and  $x_1 - x_2 = 4$ .

### 4.1 Subspaces

**Defintion:** A subset  $S$  of  $\mathbb{R}^n$  is a *subspace* if  $S$  satisfies the following 3 properties

- $S$  contains 0.
- (closed under addition) If  $u$  and  $v$  are in  $S$  then so is  $u + v$ .
- (closed under multiplication) If  $r \in \mathbb{R}$  and  $u \in S$ , then  $ru \in S$ .

**Nonexamples:**

- If  $b \neq 0$ , then  $Ax = b$  is never a subspace.
- The graph  $y = x^2$  is not a subspace.

**Example:**

- The span of any set of vectors are a subspace.
- The solutions to  $Ax = 0$  is a subspace.

Consider the matrix  $A = [3, -1, 7, -6; 4, -1, 9, -7; -2, 1, -5, 5]$ . The general solution to  $Ax = 0$  is  $x = s_1(-2, 1, 1, 0) + s_2(1, -3, 0, 1)$  So the set of solutions is the span of  $(-2, 1, 1, 0)$  and  $(1, -3, 0, 1)$ .

**Definition:** The set of solutions to  $Ax = 0$  is called the nullspace of  $A$  and is denote  $\text{null}(A)$ .

**Definition:** Let  $T : \mathbb{R}^m \rightarrow \mathbb{R}^n$  be a linear transformation. Then the set  $\{T(x) : x \in \mathbb{R}^m\}$  is called the *range* of  $T$ . This is a subspace of the codomain. If  $T$  is associated to a matrix  $A$ , then the range is the span of the columns of  $A$ .

The set  $\{x \in \mathbb{R}^m : T(x) = 0\}$  is called the kernel of  $T$ . This is a subspace of the domain.

- A linear transform is onto if it's range is equal to the codomain.
- A linear transform is one-to-one if it's kernel contains only the zero vector.