Math 308G - Winter 2018 Final 2018-03-13

Name:	
Student ID Number:	

Question	Points	Score
1	12	
2	12	
3	12	
4	12	
5	12	
6	12	
Total:	72	

- There are 5 problems on this exam. Be sure you have all 5 problems on your exam.
- The final answer must be left in exact form. Box your final answer.
- You are allowed the TI-30XIIS calculator. It is possible to complete the exam without a calculator.
- You are allowed a single sheet of 2-sided handwritten self-written notes.
- You must show your work to receive full credit. A correct answer with no supporting work will receive a zero.
- Use the backsides if you need extra space. Make a note of this if you do.
- Do not cheat. This exam should represent your own work. If you are caught cheating, I will report you to the Community Standards and Student Conduct office.

Conventions:

- I will often denote the zero vector by 0.
- ullet When I define a variable, it is defined for that whole question. The A defined in Question 2 is the same for each part.
- I treat row and column vectors as the same.
- For any linear transformation T, there exists a matrix A such that T(x) = Ax. I defined the determinant, rank, and nullity of T using A. This means,

$$det(T) = det(A)$$
, $rank(T) = rank(A)$, $nullity(T) = nullity(A)$.

- 1. Give an example of each of the following. If it is not possible, write "NOT POSSIBLE". You do not need to justify your answers.
 - (a) (2 points) If possible, give an example of a 2×2 matrix A that is not diagonalizable but A^2 is diagonalizable.
 - (b) (2 points) If possible, give an example of a 2×2 matrix A such that $A^2 = I_2$ and nullity $A = I_2$.
 - (c) (2 points) If possible, give an example of a 2×2 matrix with distinct eigenvalues that is not invertible.
 - (d) (2 points) If possible, give an example of linear transformations $T: \mathbb{R}^2 \to \mathbb{R}^2$ and $S: \mathbb{R}^2 \to \mathbb{R}^2$ such that $\operatorname{rank}(T) = \operatorname{rank}(S) = \operatorname{rank}(T \circ S) = 1$.
 - (e) (2 points) If possible, give an example a 2×4 matrix A such that rank(A) = nullity(A).
 - (f) (2 points) If possible, give an example of a 2×2 matrix A such that 1 is not an eigenvalue of A^2 but 1 is an eigenvalue of A^4 . (Think geometrically).

- 2. Perform the following computations.
 - (a) (6 points) Let

$$A = \begin{bmatrix} 1 & 0 & 2 \\ 2 & 0 & 4 \\ 0 & 1 & 1 \end{bmatrix}.$$

- What is the reduced echelon form of A?
- Does Ax = (1, 2, 1) have a solution? If so, give the general solution.
- Does Ax = (1, 1, 1) have a solution? If so, give the general solution.
- What is a basis for row(A)?
- (b) (6 points) Let

$$B = \begin{bmatrix} 2 & 0 & -1 \\ 0 & -1 & 2 \\ 0 & 0 & 1 \end{bmatrix}.$$

• What is B^{-1} ?

• What is the charateristic polynomial of B^2 ? (Hint: Be careful about the sign.)

3. Let A and B be equivalent matrices given by

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 0 & 8 \\ 0 & 1 & 1 & 3 \\ 2 & 5 & 6 & 16 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 8 \\ 0 & 0 & 1 & -5 \\ 0 & 0 & 0 & 0 \end{bmatrix} = B.$$

Denote the columns of A by a_1, a_2, a_3, a_4 .

(a) (3 points) Give a basis for null(A).

(b) (3 points) Give the general solution to $Ax = a_2$.

(c) (3 points) Give the general solution to $2Ax - a_3 = a_1 + a_2$.

$$(1/2, 1/2, 1/2, 0) + s_1(-3, -8, 5, 1)$$

(d) (3 points) It turns out $e_1 = (1, 0, 0, 0) \notin \operatorname{col}(A)$. Give a vector v such that $v \neq e_1$ and $Ax = e_1 - v$ has a solution.

4. Let $T: \mathbb{R}^3 \to \mathbb{R}^4$ and $S: \mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformations given by

$$T(x, y, z) = (x + 2z, y + z, x + y + z, z)$$

and

$$S(x, y, z) = (2x + y + z, y + z, y + z)$$

(a) (2 points) There exists a matrix A such that T(v) = Av. What is A?

(b) (2 points) There exists a matrix B such that S(v) = Bv. What is B?

- (c) (4 points) These should be quick questions.
 - What is rank(S)?
 - What is det(S)?
 - What is $\operatorname{nullity}(2S)$?
 - What are 2 different eigenvalues of S?
- (d) (4 points) Recall that $(T \circ S)(v) = T(S(v))$.
 - What is the rank of $T \circ S$?
 - What is a basis for range($T \circ S$)? (Hint: Look at the 2nd two columns of B).

5. Let

$$A = \begin{bmatrix} 0 & -1 & 3 & 0 \\ 0 & -1 & 3 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

be a matrix which decomposes as $A = UDU^{-1}$, where

$$U = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}, \quad D = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}.$$

Let u_1, u_2, u_3, u_4 be the columns of U and $\mathcal{B} = \{u_1, u_2, u_3, u_4\}$.

(a) (6 points) Fill out the following table.

Eigenvalue λ	Alg. Multiplicity of λ	Geo. Multiplicity of λ	A Basis for E_{λ}

(b) (3 points) What is a basis for range(A)?

(c) (3 points) Let $x = u_1 + u_2 + u_3$. What is $[A^{18}x]_{\mathcal{B}}$? You are allowed to have exponents in your answer.

- 6. Let A, u_1, u_2, u_3, u_4 be as defined in Question 5.
 - (a) (2 points) What is det(A)?

(b) (2 points) What is det(A + 2I)?

(c) (2 points) What is rank(A)?

(d) (2 points) What is rank(A - 2I)?

(e) (2 points) Does $Ax = -u_2 + u_3 - 4u_4$ have a solution? If so, express it as a linear combination of u_1, u_2, u_3, u_4 .

(f) (2 points) Does $Ax = 2u_1 + u_2 + u_3$ have a solution? If so, express it as a linear combination of u_1, u_2, u_3, u_4 .